

State Merging with Quantifiers in Symbolic Execution



David
Trabish¹



Noam
Rinetzky¹



Sharon
Shoham¹



Vaibhav
Sharma²

¹Tel Aviv University, Israel

²University of Minnesota, USA

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Symbolic Execution: Introduction

Program analysis technique

- Systematically explores paths
- Checks feasibility using SMT



Main challenges

- Path explosion
- Constraint solving



SAMSUNG



Symbolic Execution: State Merging

- Mitigates path explosion by joining exploration paths
- Often leads to:
 - **Large disjunctive** constraints
 - Costly constraint solving

Main Contributions

- State merging using **compact quantified** constraints
- Specialized solving procedure

$(\ldots) \vee (\ldots) \vee \dots \vee (\ldots)$



$\forall x. (\ldots)$

Example

```
int strspn(char *s, char c) {  
    int count = 0;  
    while (s[count] == c) {  
        count++;  
    }  
    return count;  
}
```

```
// symbolic, null-terminated  
char s[3];  
int n = strspn(s, 'a');  
int m = strspn(s + n, 'b');  
...
```



Example

```
int strspn(char *s, char c) {  
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...
```



{*count* ↦ 0} 

Example

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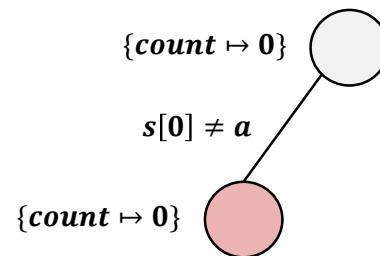


{*count* ↦ 0} 

Example

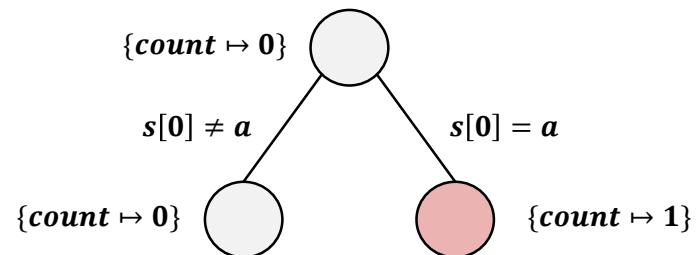
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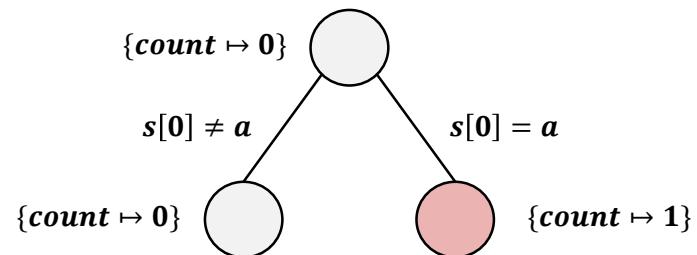
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Example

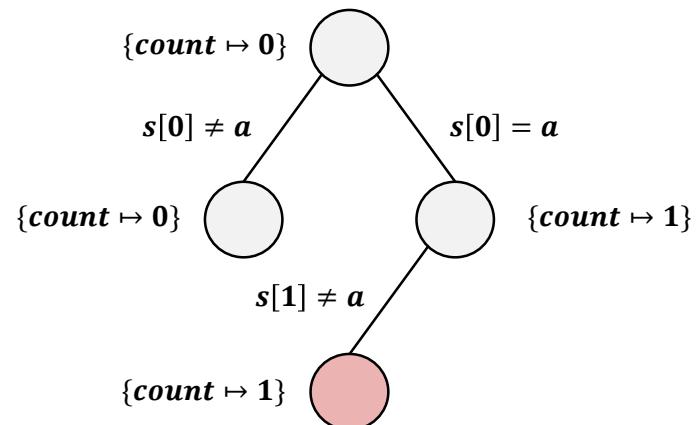
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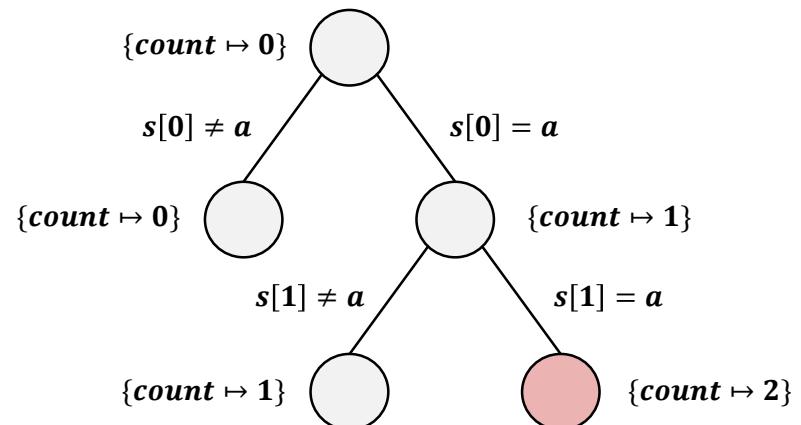
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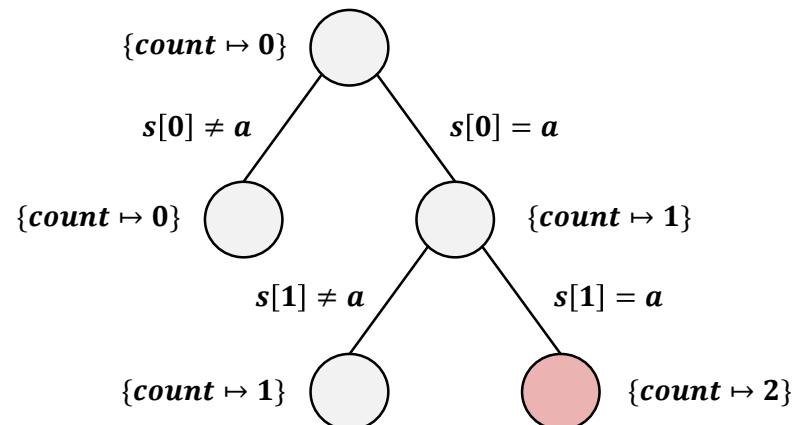
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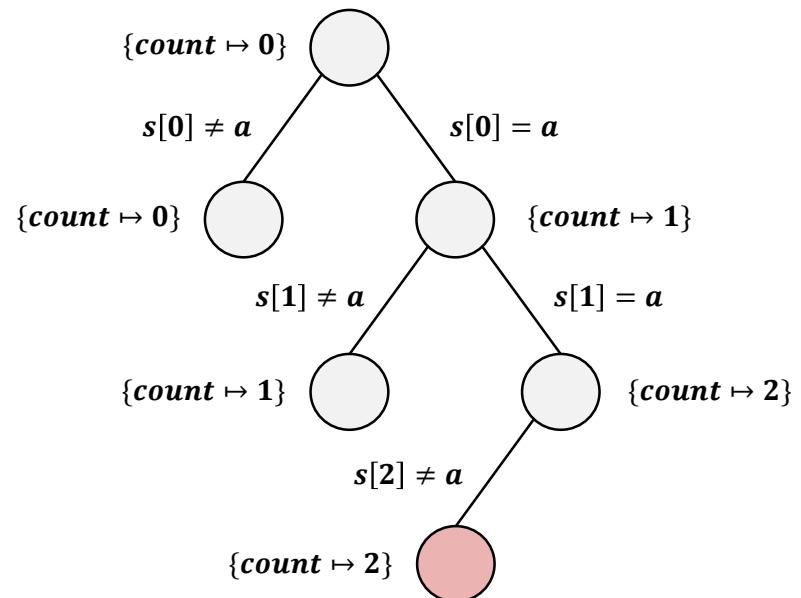
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Example

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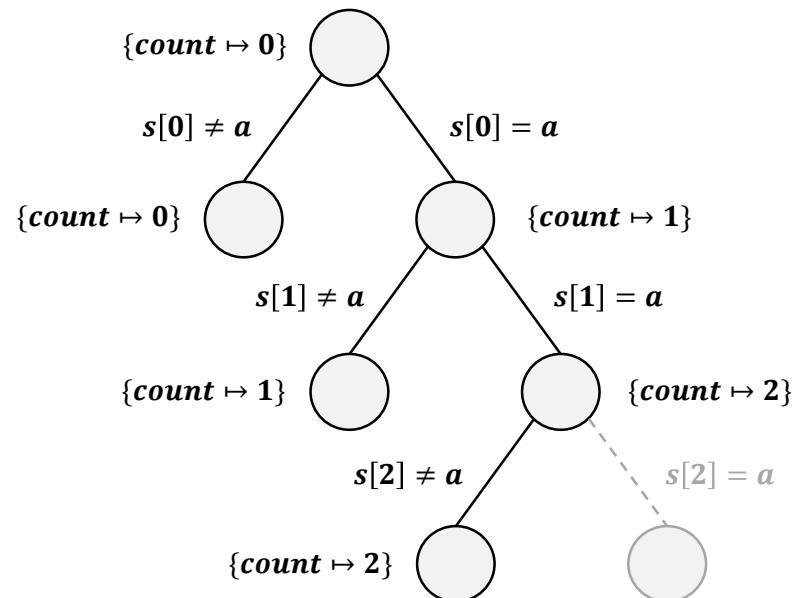
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Example

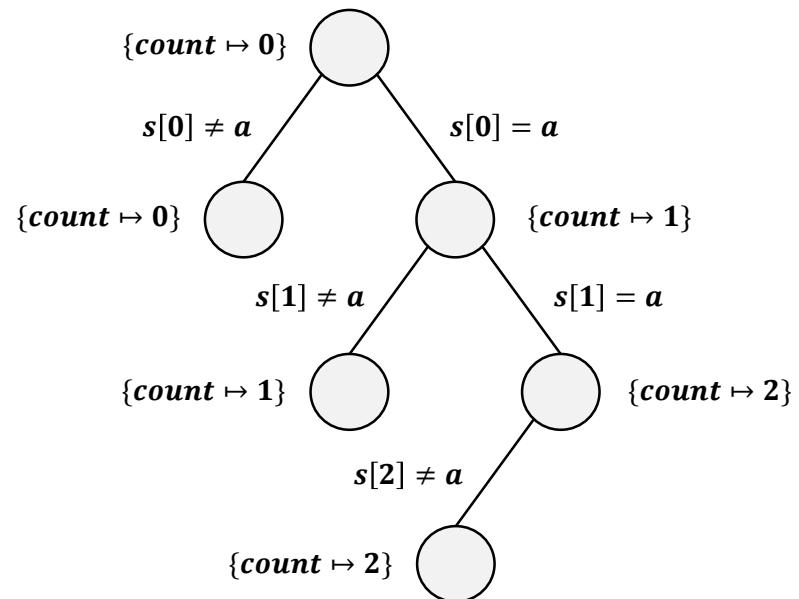
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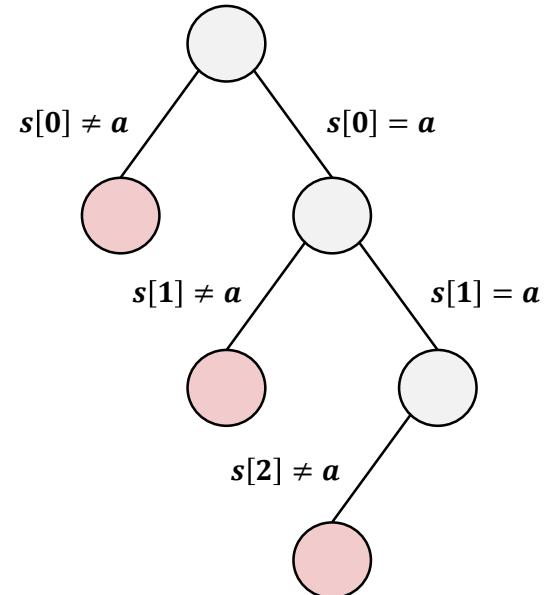
Example

```
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Standard State Merging

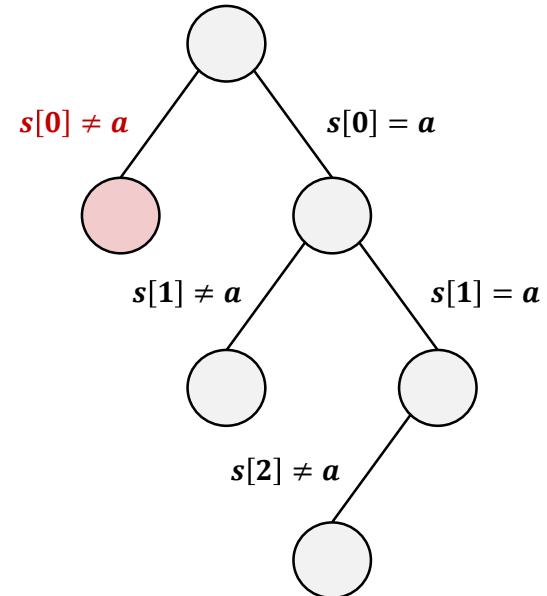
Merging the path constraints



Standard State Merging

Merging the path constraints

$$s[0] \neq a$$

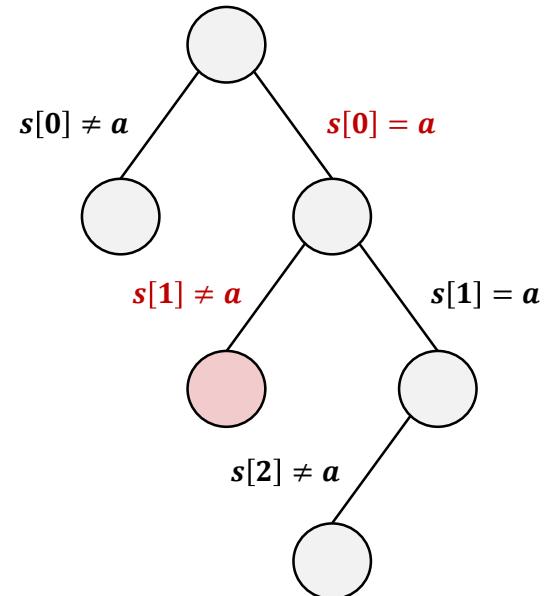


Standard State Merging

Merging the path constraints

$$s[0] \neq a$$

$$s[0] = a \wedge s[1] \neq a$$



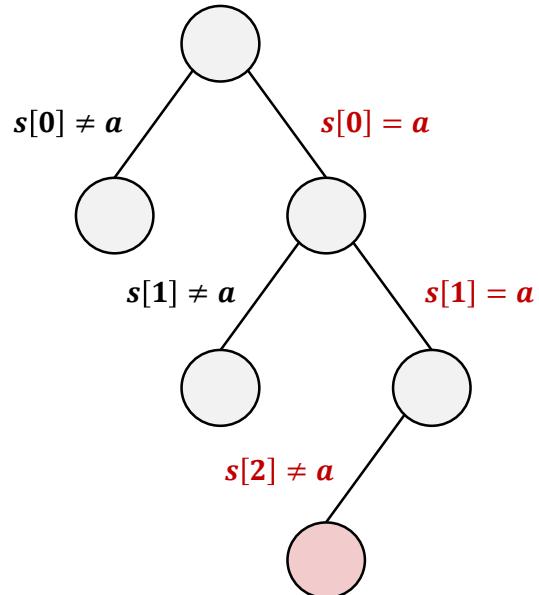
Standard State Merging

Merging the path constraints

$$s[0] \neq a$$

$$s[0] = a \wedge s[1] \neq a$$

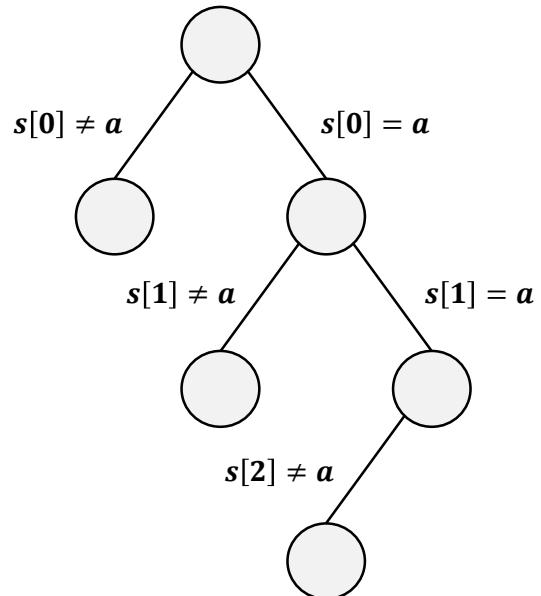
$$s[0] = a \wedge s[1] = a \wedge s[2] \neq a$$



Standard State Merging

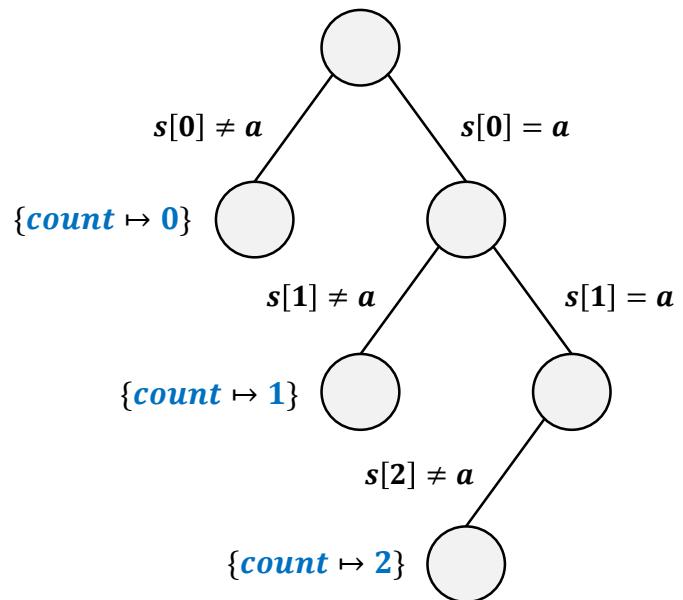
Merging the path constraints

$$\begin{aligned}(s[0] \neq a) \vee \\(s[0] = a \wedge s[1] \neq a) \vee \\(s[0] = a \wedge s[1] = a \wedge s[2] \neq a)\end{aligned}$$



Standard State Merging

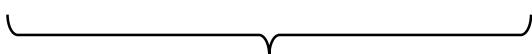
Merging the memory

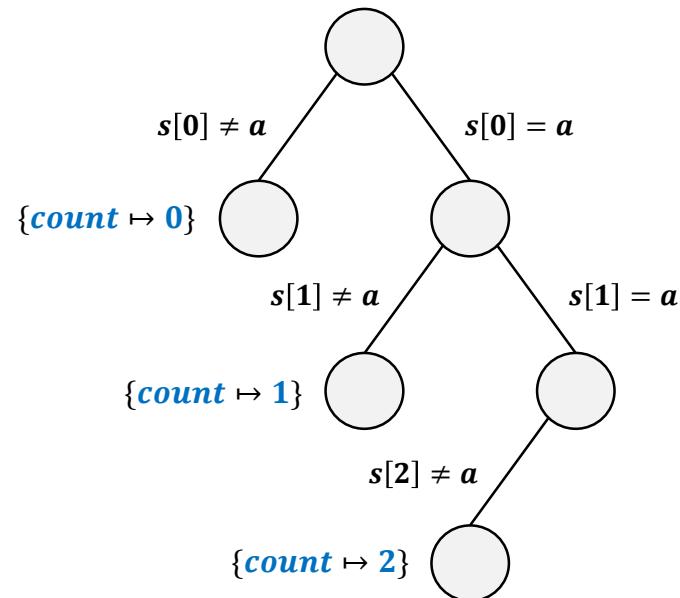


Standard State Merging

Merging the memory

```
ite(  
    s[0] ≠ a,  
    0,  
    ...  
)
```

merged value of **count**

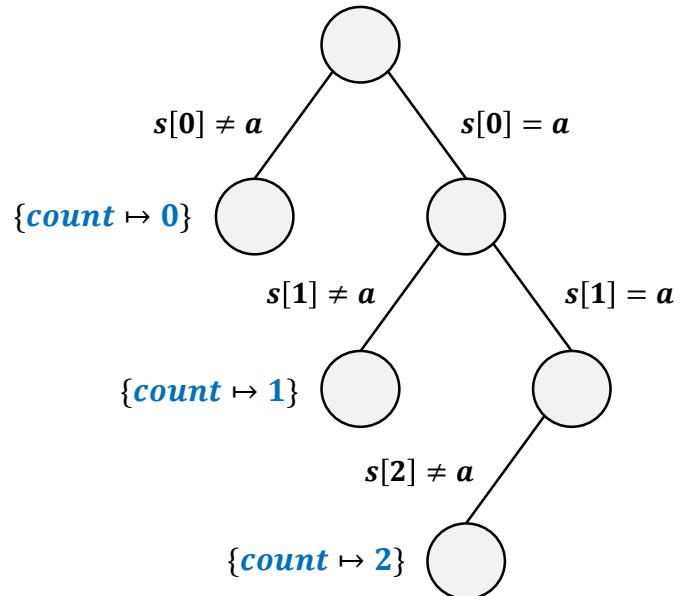


Standard State Merging

Merging the memory

```
ite(  
    s[0] ≠ a,  
    0,  
    ite(  
        s[0] = a ∧ s[1] ≠ a,  
        1,  
        ...  
    )  
)  
} {count ↪ 0}
```

merged value of **count**

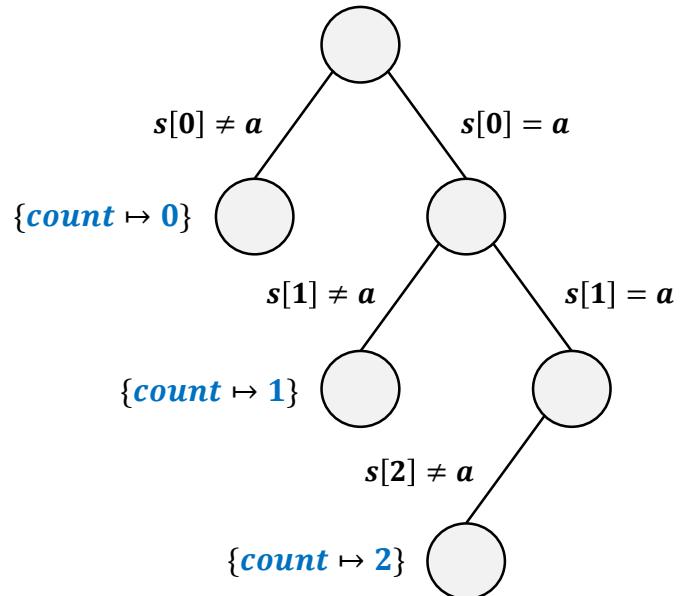


Standard State Merging

Merging the memory

```
ite(  
    s[0] ≠ a,  
    0,  
    ite(  
        s[0] = a ∧ s[1] ≠ a,  
        1,  
        2  
    )  
)  
} {count ↪ 0}
```

merged value of **count**



Standard State Merging

```
int strspn(char *s, char c) {  
    int count = 0;  
    while (s[count] == c) {  
        count++;  
    }  
    return count;  
}
```

// symbolic, null-terminated
char s[3];
int n = strspn(s, 'a');
int m = strspn(s + n, 'b');
...

```
ite(  
    s[0] != a,  
    0,  
    ite(  
        s[0] = a ∧ s[1] ≠ a,  
        1,  
        2  
    )  
)
```

Standard State Merging

```
int strspn(char *s, char c) {  
    int count = 0;  
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```
// symbolic, null-terminated  
char s[3];  
int n = strspn(s, 'a');  
int m = strspn(s + n, 'b');  
...
```

```
ite(  
    s[0] != a,  
    0,  
    ite(  
        s[0] = a & s[1] != a,  
        1,  
        2  
    )  
)
```

Standard State Merging

```
int strspn(char *s, char c) {  
    int count = 0;  
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```
ite(  
    s[0] != a,  
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        1,  
        2  
    )  
)
```

Standard State Merging

Path constraints

```
... ∧  
(s[ite(s[0] ≠ a, 0, ite(s[0] = a ∧ s[1] ≠ a, 1,2)) + 0] ≠ a) ∨  
(s[ite(s[0] ≠ a, 0, ite(s[0] = a ∧ s[1] ≠ a, 1,2)) + 0] = a ∧ s[ite(s[0] ≠ a, 0, ite(s[0] = a ∧ s[1] ≠ a, 1,2)) + 1] ≠ a) ∨  
(s[ite(s[0] ≠ a, 0, ite(s[0] = a ∧ s[1] ≠ a, 1,2)) + 0] = a ∧ s[ite(s[0] ≠ a, 0, ite(s[0] = a ∧ s[1] ≠ a, 1,2)) + 1] = a ∧ s[ite(s[0] ≠ a, 0, ite(s[0] = a ∧ s[1] ≠ a, 1,2)) + 2] ≠ a)
```

Value of m

```
ite(  
    s[ite(s[0] ≠ a, 0, ite(s[0] = a ∧ s[1] ≠ a, 1,2)) + 0] ≠ a,  
    0,  
    ite(  
        s[ite(s[0] ≠ a, 0, ite(s[0] = a ∧ s[1] ≠ a, 1,2)) + 0] = a ∧ s[ite(s[0] ≠ a, 0, ite(s[0] = a ∧ s[1] ≠ a, 1,2)) + 1] ≠ a,  
        1,  
        2  
    )  
)
```

State Merging with Quantifiers

Merging the path constraints

```
int strspn(char *s, char c) {  
    int count = 0;  
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```
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char s[3];  
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...
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State Merging with Quantifiers

Merging the path constraints

$$\begin{aligned}(s[0] \neq a) \vee \\(s[0] = a \wedge s[1] \neq a) \vee \\(s[0] = a \wedge s[1] = a \wedge s[2] \neq a)\end{aligned}$$

State Merging with Quantifiers

Merging the path constraints

$$\begin{aligned} & (s[0] \neq a) \vee \\ & (s[0] = a \wedge s[1] \neq a) \vee \\ & (s[0] = a \wedge s[1] = a \wedge s[2] \neq a) \end{aligned}$$

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$$s[0] = a \wedge \cdots \wedge s[i-1] = a \wedge s[i] \neq a$$

State Merging with Quantifiers

Merging the path constraints

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$$s[0] = a \wedge \cdots \wedge s[i-1] = a \wedge s[i] \neq a$$

↑

$$(\forall x. 1 \leq x \leq i \rightarrow s[x-1] = a) \wedge s[i] \neq a$$

bound variable

State Merging with Quantifiers

Merging the path constraints

$$\begin{aligned} & (s[0] \neq a) \vee \\ & (s[0] = a \wedge s[1] \neq a) \vee \\ & (s[0] = a \wedge s[1] = a \wedge s[2] \neq a) \\ & \Updownarrow \\ & ((\forall x. 1 \leq x \leq 0 \rightarrow s[x - 1] = a) \wedge s[0] \neq a) \vee \\ & ((\forall x. 1 \leq x \leq 1 \rightarrow s[x - 1] = a) \wedge s[1] \neq a) \vee \\ & ((\forall x. 1 \leq x \leq 2 \rightarrow s[x - 1] = a) \wedge s[2] \neq a) \end{aligned}$$

State Merging with Quantifiers

Merging the path constraints

$$(s[0] \neq a) \vee$$

$$(s[0] = a \wedge s[1] \neq a) \vee$$

$$(s[0] = a \wedge s[1] = a \wedge s[2] \neq a)$$

\Updownarrow

$$((\forall x. 1 \leq x \leq 0 \rightarrow s[x - 1] = a) \wedge s[0] \neq a) \vee$$

$$((\forall x. 1 \leq x \leq 1 \rightarrow s[x - 1] = a) \wedge s[1] \neq a) \vee$$

$$((\forall x. 1 \leq x \leq 2 \rightarrow s[x - 1] = a) \wedge s[2] \neq a)$$

\Updownarrow

$$0 \leq i \leq 2 \wedge (\forall x. 1 \leq x \leq i \rightarrow s[x - 1] = a) \wedge s[i] \neq a$$

fresh free variable

State Merging with Quantifiers

Merging memory

$$0 \leq i \leq 2 \wedge (\forall x. 1 \leq x \leq i \rightarrow s[x - 1] = a) \wedge s[i] \neq a$$

merged value of n {

$$\begin{aligned} & ite(\\ & \quad s[0] \neq a, \\ & \quad 0, \\ & \quad ite(\\ & \quad \quad s[0] = a \wedge s[1] \neq a, \\ & \quad \quad 1, \\ & \quad \quad 2 \\ & \quad) \\ &) \end{aligned}$$

State Merging with Quantifiers

Merging memory

$$0 \leq i \leq 2 \wedge (\forall x. 1 \leq x \leq i \rightarrow s[x - 1] = a) \wedge s[i] \neq a$$

merged value of n

$$\left\{ \begin{array}{l} ite(\\ \quad s[0] \neq a, \\ \quad 0, \\ \quad ite(\\ \quad \quad s[0] = a \wedge s[1] \neq a, \\ \quad \quad 1, \\ \quad \quad 2 \\ \quad) \\) \end{array} \right.$$

State Merging with Quantifiers

Merging memory

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merged value of n {

$$\begin{aligned} & ite(\\ & \quad s[0] \neq a, \\ & \quad 0, \\ & \quad ite(\\ & \quad \quad s[0] = a \wedge s[1] \neq a, \quad \Rightarrow \quad i \\ & \quad \quad 1, \\ & \quad \quad 2 \\ & \quad) \\ &) \end{aligned}$$

State Merging with Quantifiers

Merging the path constraints

```
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```

```
// symbolic, null-terminated  
char s[3];  
int n = strspn(s, 'a');  
int m = strspn(s + n, 'b');  
...
```

State Merging with Quantifiers

Path constraints

$$\dots \wedge 0 \leq j \leq 2 \wedge (\forall x. 1 \leq x \leq j \rightarrow s[i + x - 1] = b) \wedge s[i + j] \neq b$$

Value of m

$$j$$

Synthesizing Quantified Constraints

path constraints

$$(s[0] \neq a)$$

$$(s[0] = a \wedge s[1] \neq a)$$

$$(s[0] = a \wedge s[1] = a \wedge s[2] \neq a)$$

Synthesizing Quantified Constraints

path constraints

$$(s[0] \neq a)$$

$$(s[0] = a \wedge s[1] \neq a)$$

$$(s[0] = a \wedge s[1] = a \wedge s[2] \neq a)$$



abstraction

$$\beta$$

$$\alpha\beta$$

$$\alpha\alpha\beta$$

Synthesizing Quantified Constraints

path constraints

$$(s[0] \neq a)$$

$$(s[0] = a \wedge s[1] \neq a)$$

$$(s[0] = a \wedge s[1] = a \wedge s[2] \neq a)$$



abstraction

$$\begin{array}{ll} \beta & \alpha^0 \beta \\ \alpha\beta & \alpha^1 \beta \\ \alpha\alpha\beta & \alpha^2 \beta \end{array} \left. \right\} \alpha^* \beta$$

Synthesizing Quantified Constraints

path constraints

$$(s[0] \neq a)$$

$$(s[0] = a \wedge s[1] \neq a)$$

$$(s[0] = a \wedge s[1] = a \wedge s[2] \neq a)$$



abstraction

$$\begin{array}{ll} \beta & \alpha^0 \beta \\ \alpha\beta & \alpha^1 \beta \\ \alpha\alpha\beta & \alpha^2 \beta \end{array} \left\} \alpha^* \beta \quad \Rightarrow \quad \right.$$

synthesis constraints

$$\begin{aligned} \varphi_\alpha(1) &\stackrel{\text{def}}{=} s[0] = a \\ \varphi_\alpha(2) &\stackrel{\text{def}}{=} s[1] = a \end{aligned} \Rightarrow \varphi_\alpha(x) \stackrel{\text{def}}{=} s[x-1] = a$$

$$\varphi_\beta(0) \stackrel{\text{def}}{=} s[0] \neq a$$

$$\varphi_\beta(1) \stackrel{\text{def}}{=} s[1] \neq a \Rightarrow \varphi_\beta(x) \stackrel{\text{def}}{=} s[x] \neq a$$

$$\varphi_\beta(2) \stackrel{\text{def}}{=} s[2] \neq a$$

Synthesizing Quantified Constraints

path constraints

$$(s[0] \neq a)$$

$$(s[0] = a \wedge s[1] \neq a)$$

$$(s[0] = a \wedge s[1] = a \wedge s[2] \neq a)$$



abstraction

$$\begin{array}{ll} \beta & \alpha^0 \beta \\ \alpha\beta & \alpha^1 \beta \\ \alpha\alpha\beta & \alpha^2 \beta \end{array} \left\{ \begin{array}{l} \alpha^* \beta \end{array} \right.$$



quantified path constraints

$$0 \leq i \leq 2 \wedge (\forall x. 1 \leq x \leq i \rightarrow \varphi_\alpha[x]) \wedge \varphi_\beta[i]$$



synthesis constraints

$$\varphi_\alpha(1) \stackrel{\text{def}}{=} s[0] = a$$

$$\varphi_\alpha(2) \stackrel{\text{def}}{=} s[1] = a$$

$$\Rightarrow \varphi_\alpha(x) \stackrel{\text{def}}{=} s[x-1] = a$$

$$\varphi_\beta(0) \stackrel{\text{def}}{=} s[0] \neq a$$

$$\varphi_\beta(1) \stackrel{\text{def}}{=} s[1] \neq a$$

$$\Rightarrow \varphi_\beta(x) \stackrel{\text{def}}{=} s[x] \neq a$$

$$\varphi_\beta(2) \stackrel{\text{def}}{=} s[2] \neq a$$

Synthesizing Quantified Constraints

path constraints

$$\begin{aligned} (s[0] \neq a) \vee & \\ (s[0] = a \wedge s[1] \neq a) \vee & \\ (s[0] = a \wedge s[1] = a \wedge s[2] \neq a) & \end{aligned} \quad \Leftrightarrow \quad \begin{aligned} 0 \leq i \leq 2 \wedge (\forall x. 1 \leq x \leq i \rightarrow \varphi_\alpha[x]) \wedge \varphi_\beta[i] \end{aligned}$$



abstraction

$$\begin{array}{ll} \beta & \alpha^0\beta \\ \alpha\beta & \left. \begin{array}{l} \alpha^1\beta \\ \alpha^2\beta \end{array} \right\} \alpha^*\beta \end{array} \Rightarrow$$

quantified path constraints

$$0 \leq i \leq 2 \wedge (\forall x. 1 \leq x \leq i \rightarrow \varphi_\alpha[x]) \wedge \varphi_\beta[i]$$



synthesis constraints

$$\begin{aligned} \varphi_\alpha(1) &\stackrel{\text{def}}{=} s[0] = a \\ \varphi_\alpha(2) &\stackrel{\text{def}}{=} s[1] = a \Rightarrow \varphi_\alpha(x) \stackrel{\text{def}}{=} s[x - 1] = a \end{aligned}$$

$$\varphi_\beta(0) \stackrel{\text{def}}{=} s[0] \neq a$$

$$\varphi_\beta(1) \stackrel{\text{def}}{=} s[1] \neq a \Rightarrow \varphi_\beta(x) \stackrel{\text{def}}{=} s[x] \neq a$$

$$\varphi_\beta(2) \stackrel{\text{def}}{=} s[2] \neq a$$

Additional Contributions

Specialized solving procedure

- Efficiently solving quantified formulas

Incremental state merging

- Handling complex loops (exponential execution trees)

More details in the paper...

Evaluation

Implementation

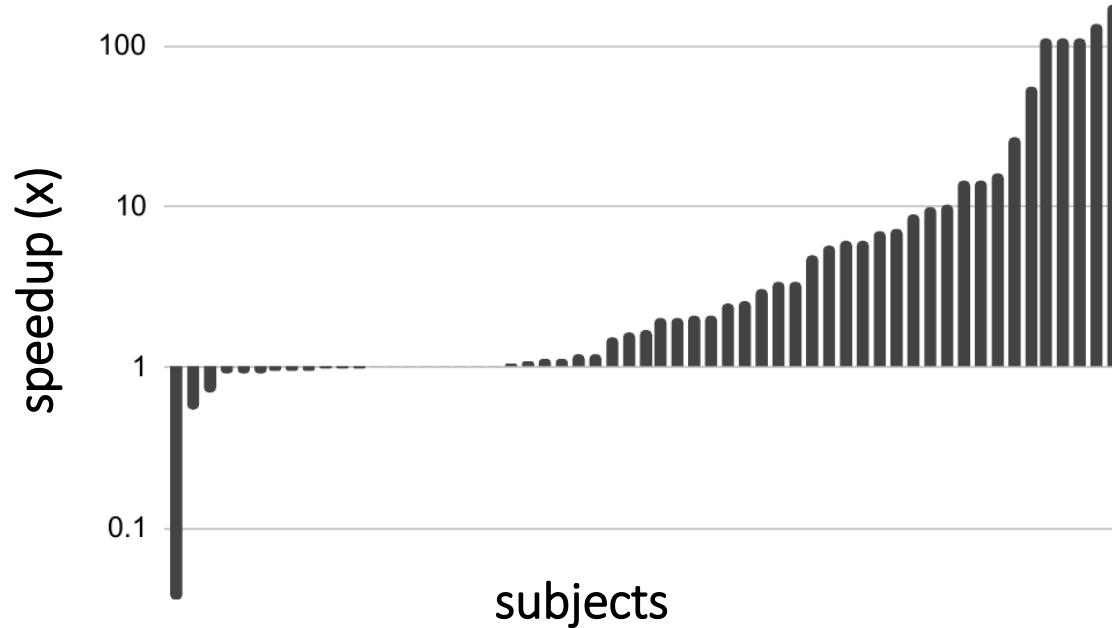
- On top of *KLEE*

Benchmarks

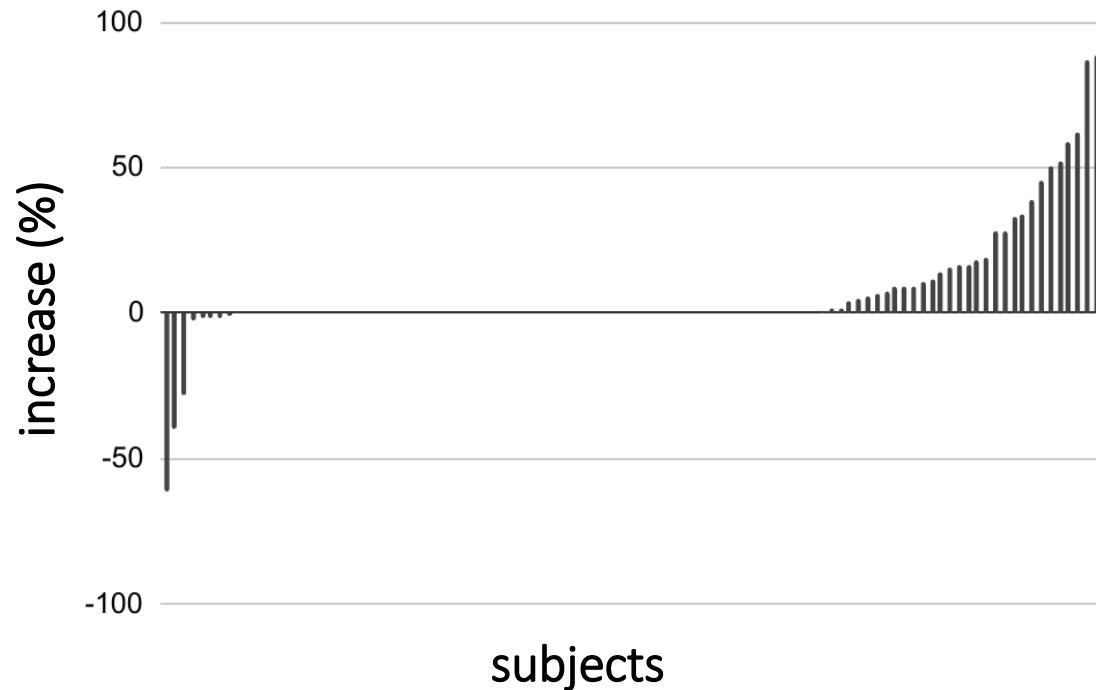
- GNU oSIP (*35 subjects*)
- wget (*31 subjects*)
- GNU libtasn1 (*13 subjects*)
- libpng (*12 subjects*)
- APR (Apache Portable Runtime) (*20 subjects*)
- json-c (*5 subjects*)
- busybox (*30 subjects*)



Evaluation: Analysis Time



Evaluation: Coverage



Found Bugs

Detected bugs in *klee-uclibc* in the experiments with *busybox*

- Two *memory out-of-bound's*
- Confirmed and fixed

Summary

- State merging using quantified constraints
- Specialized solving procedure for quantified constraints
- Evaluated on real-world benchmarks
- Found bugs



<https://github.com/davidtr1037/klee-quantifiers>